

5.44

mass of tup: 2000 kg,
mass of frame: 20000 kg,
mass of anvil: 30000 kg,
mass of foundation block: 65000 kg,
stiffness of elastic pad: 1 GPa,
stiffness of isolation: 500 MPa,
striking velocity of tup: 4.5 m/s.

Solution:

(a) Natural frequencies of the system:

From problem 5.1,

$$\omega_{1,2}^2 = \frac{k_1 + k_2}{2 m_1} + \frac{k_2}{2 m_2} \pm \sqrt{\frac{1}{4} \left(\frac{k_1 + k_2}{m_1} + \frac{k_2}{m_2} \right)^2 - \frac{k_1 k_2}{m_1 m_2}}$$

$$\omega_{1,2}^2 = \frac{1.5 \times 10^9}{130000} + \frac{10^9}{100000} \pm \sqrt{\frac{1}{4} \left(\frac{1.5 \times 10^9}{65000} + \frac{10^9}{50000} \right)^2 - \frac{500 \times 10^{15}}{3.25 \times 10^9}}$$

or $\omega_1 = 62.6894 \text{ rad/sec.}$

$\omega_2 = 197.8559 \text{ rad/sec.}$

(b) Initial conditions of the system:

Let $\dot{\theta}_2$ = initial velocity of anvil and frame just after the impact of tup.

From conservation of momentum principle, momentum of tup plus momentum of m_2 just before impact = momentum of tup plus momentum of m_2 just after impact.

i.e. $m_{\text{tup}} \dot{\theta}_{\text{tup}} + m_2 (0) = m_{\text{tup}} \dot{\theta}_0 + m_2 \dot{\theta}_2$ (E₁)

where $\dot{\theta}_0$ = velocity of rebound of tup after impact

Also,

$$\text{Coefficient of restitution (e)} = \left(\frac{\text{relative velocity after impact}}{\text{relative velocity before impact}} \right)$$

i.e. $e = \frac{\dot{\theta}_2 - \dot{\theta}_0}{\dot{\theta}_{\text{tup}}} \quad \text{or} \quad \dot{\theta}_0 = \dot{\theta}_2 - e \dot{\theta}_{\text{tup}}$ (E₂)

From Eqs. (E₁) and (E₂),

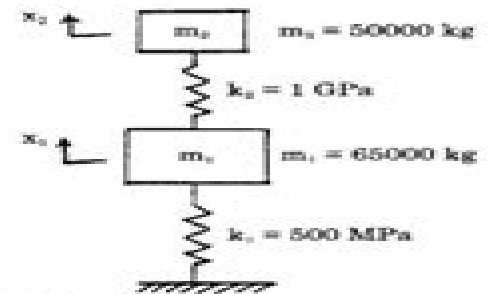
$$\dot{\theta}_2 = \frac{m_{\text{tup}} \dot{\theta}_{\text{tup}} (1 + e)}{m_{\text{tup}} + m_2}$$

For given data,

$$\dot{\theta}_2 = \frac{2000 (-4.5) (1 + 0.5)}{2000 + 50000} = -0.2596 \text{ m/s}$$

$\therefore$ Initial conditions are:

$$x_1(0) = 0, \quad \dot{x}_1(0) = 0, \quad x_2(0) = 0, \quad \dot{x}_2(0) = -0.2596 \text{ m/s.}$$



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M Walker



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[Introduction to Inverse Problems for Differential Equations](#) Alemdar Hasanov Hasanoglu, Vladimir G. Romanov, 2021-08-02 This book presents a systematic exposition of the main ideas and methods in treating inverse problems for PDEs arising in basic mathematical models though it makes no claim to being exhaustive Mathematical models of most physical phenomena are governed by initial and boundary value problems for PDEs and inverse problems governed by these equations arise naturally in nearly all branches of science and engineering The book's content especially in the Introduction and Part I is self contained and is intended to also be accessible for beginning graduate students whose mathematical background includes only basic courses in advanced calculus PDEs and functional analysis Further the book can be used as the backbone for a lecture course on inverse and ill posed problems for partial differential equations In turn the second part of the book consists of six nearly independent chapters The choice of these chapters was motivated by the fact that the inverse coefficient and source problems considered here are based on the basic and commonly used mathematical models governed by PDEs These chapters describe not only these inverse problems but also main inversion methods and techniques Since the most distinctive features of any inverse problems related to PDEs are hidden in the properties of the corresponding solutions to direct problems special attention is paid to the investigation of these properties For the second edition the authors have added two new chapters focusing on real world applications of inverse problems arising in wave and vibration phenomena They have also revised the whole text of the first edition

Computational Methods in Nonlinear Structural and Solid Mechanics Ahmed K. Noor, Harvey G. McComb, 2014-05-20 Computational Methods in Nonlinear

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