Planar Multibod **Dynamics**

Formulation, **Programming** with MATLAB, and Applications 0.013 0.015 k, L 0, d c, f a) "f A1: n2 = s rot(s B2)" f

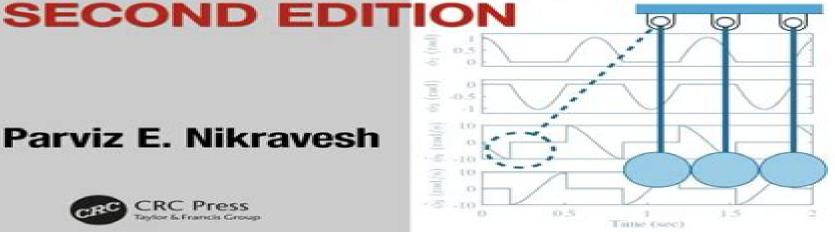
npute global components of s_A1 and

's A1 local; s B2 = A2's B2 lc

ACRES.

Parviz E. Nikravesh





Planar Multibody Dynamics Formulation Applications

RC Schank

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