

```

function RECURSIVE-BEST-FIRST-SEARCH(problem) returns a solution, or failure
  return RBFS(problem, MAKE-NODE(problem, INITIAL-STATE),  $\infty$ )

function RBFS(problem, node, f-limit) returns a solution, or failure and a new f-cost limit
  if problem.GOAL-TEST(node.STATE) then return SOLUTION(node)
  successors  $\leftarrow []$ 
  for each action in problem.ACTIONS(node.STATE) do
    add CHILD-NODE(problem, node, action) into successors
  if successors is empty then return failure,  $\infty$ 
  best  $\leftarrow$  MINIMAX-VALUE(problem, node, f-limit, 0, 0, 0)
  new-f-limit  $\leftarrow$  best.f-cost
  return best.action, new-f-limit

```

Figure 3.5.6 The recursive best-first search algorithm.

Figure 3.5.6 shows one of many. For this reason, RB is not presented for pseudocode. In fact, there are numerous algorithms that implement the same problem without requiring explicitly an implementation of a minimax or maximax node. We discuss these next.

3.5.2 Iterative Deepening Search

The simplest way to reduce memory requirements for RB is to allow the idea of iterative deepening in the heuristic search context, resulting in the **Iterative Deepening RB** (IDRB) algorithm. The main difference between IDB* and iterative heuristic deepening is that the search controls the f -costing, ∞ rather than the depth, as with IDB*. The search stops when the search reaches a node with f -cost less than or equal to the f -cost of the previous iteration. IDB* is presented for heuristic problems with only one node per level. The algorithm is modified accordingly to handle multiple children of nodes. Unfortunately, it differs from the more efficient and more robust IDB* in that the heuristic values of children are search described in Figure 3.5.7. The algorithm is similar to other iterative heuristic algorithms, such as IDB* and IDA*.

Iterative Deepening Search (IDRB) is a simple iterative algorithm that attempts to solve the problem of searching for the search tree using only those given. The algorithm is shown in Figure 3.5.8. Its operation is similar to that of a minimax depth-first search. The algorithm maintains a f -costing, ∞ rather than the depth, as with IDB*. The search stops when the search reaches a node with f -cost less than or equal to the f -cost of the previous iteration. IDB* is presented for heuristic problems with only one node per level. The algorithm is modified accordingly to handle multiple children of nodes. Unfortunately, it differs from the more efficient and more robust IDB* in that the heuristic values of children are search described in Figure 3.5.7. The algorithm is similar to other iterative heuristic algorithms, such as IDB* and IDA*.

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The Cambridge Handbook of Facial Recognition in the Modern State Rita Matulionyte, Monika Zalnieriute, 2024-03-27 In situations ranging from border control to policing and welfare governments are using automated facial recognition technology FRT to collect taxes prevent crime police cities and control immigration FRT involves the processing of a person's facial image usually for identification categorisation or counting This ambitious handbook brings together a diverse group of legal computer communications and social and political science scholars to shed light on how FRT has been developed used by public authorities and regulated in different jurisdictions across five continents Informed by their experiences working on FRT across the globe chapter authors analyse the increasing deployment of FRT in public and private life The collection argues for the passage of new laws rules frameworks and approaches to prevent harms of FRT in the modern state and advances the debate on scrutiny of power and accountability of public authorities which use FRT This book is also available as Open Access on Cambridge Core

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