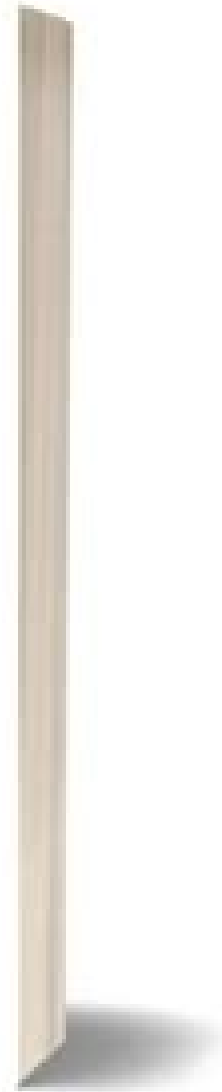


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testing different controllers P PI PD PID controllers with the machine As it turned out to be a stable system as per Routh Hurwitz Stability Criterion different controllers has been used to evaluate the Step response of Open loop Closed loop system with simulated result Controller tuning has been done to find the best result for controlling speed of SEDM Settling time % Overshoot Steady State error Rise time has been calculated for all the controllers Later active RC realization of the best fitted controller has been done using Ideal PID Control Algorithm

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