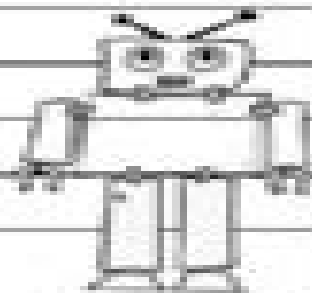


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Systems and Information Processing Fuchun Sun,Angelo Cangelosi,Jianwei Zhang,Yuanlong Yu,Huaping Liu,Bin Fang,2023-02-23 This book constitutes the refereed proceedings of the 7th International Conference on Cognitive Systems and Information Processing ICCSIP 2022 held in Fuzhou China during November 18 20 2022 The 47 papers included in this book were carefully reviewed and selected from 121 submissions They were organized in the following topical sections as follows Award Algorithm Application Manipulation Hardware and Vision *Objects to Learn about and Objects for Learning 1* Joel Bisault,Roselyne Le Bourgeois,Jean-Francois Themines,Mickael Le Mentec,Celine Chauvet-Chanoine,2022-03-09 Resulting from a conference that took place in Amiens France in June 2019 this book examines the place and role of objects centered in teaching practices from kindergarten to university both in the context of France and elsewhere These objects for learning are considered in their physicality as productions work or signs that are used for learning They become objects to learn about when the object itself is the learning objective This book offers a cross disciplinary perspective linking the different disciplinary fields studied and the many reference sources used by the authors This two volume work offers an overview of current research on the subject with this first volume introducing the questions addressed and then going on to investigate the relationship between objects and languages looking at objects at the heart of early learning **First Grade Fun Robot Composition Notebook** Carebook Publishing,2018-07-17 Express creativity with the First Grade Fun Composition Notebook The vibrant colored robot will brighten any school supplies The wide ruled writing paper is perfect for first grade elementary school students This composition notebook is an excellent choice for all children who like robots **Bioinspired Design and Control of Robots with Intrinsic Compliance** Yongping Pan,Zhao Guo,Dongbing Gu,2020-12-04 This eBook is a collection of articles from a Frontiers Research Topic Frontiers Research Topics are very popular trademarks of the Frontiers Journals Series they are collections of at least ten articles all centered on a particular subject With their unique mix of varied contributions from Original Research to Review Articles Frontiers Research Topics unify the most influential researchers the latest key findings and historical advances in a hot research area Find out more on how to host your own Frontiers Research Topic or contribute to one as an author by contacting the Frontiers Editorial Office frontiersin.org about contact [Building Your Own Robots](#) Gordon McComb,2016-08-16 Fun robotics projects that teach kids to make hack and learn There s no better way for kids to learn about the world around them than to test how things work Building Your Own Robots presents fun robotics projects that children aged 7 11 can complete with common household items and old toys The projects introduce core robotics concepts while keeping tasks simple and easy to follow and the vivid full color graphics keep your kid s eyes on the page as they work through the projects Brought to you by the trusted For Dummies brand this kid focused book offers your child a fun and easy way to start learning big topics They ll gain confidence as they design and build a self propelled vehicle hack an old remote control car to create a motorized robot and use simple commands to build and program a virtual robot all while working on their own and enjoying a sense of accomplishment

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Open-source Software for Robot Intelligence and Autonomy Daniele Pucci,Vadim Tikhonoff,Ugo Pattacini,Maxime Petit,Lorenzo Jamone,2020-02-25 Intelligence and autonomy are among the most extraordinary capacities blossomed by human evolution Yet endowing humanoid robots with these two crucial capabilities is still one of the biggest problems for the robotics community despite decades of research On the software side algorithms for artificial intelligence are still at an embryonic stage On the hardware side robotic actuators are a far cry from the muscular human system in terms of flexibility and adaptability which in turn reduces autonomy and robustness Underneath the nature of algorithms for intelligence and technology for autonomy the importance of efficient scalable implementations of robust software goes without saying Among the large variety of humanoid robots the iCub has emerged as one of the most diffused research platforms It has been developed as part of the RobotCub EU project and subsequently adopted by more than 35 laboratories worldwide Collaborations across laboratories are encouraged by writing code and libraries openly available As a consequence iCub is considered to be the ideal platform for experimenting and advancing open source software for research in several domains ranging from motor control to cognitive systems **Mechanics of Robotic Manipulation** Matthew T. Mason,2001-06-08

The science and engineering of robotic manipulation Manipulation refers to a variety of physical changes made to the world around us Mechanics of Robotic Manipulation addresses one form of robotic manipulation moving objects and the various processes involved grasping carrying pushing dropping throwing and so on Unlike most books on the subject it focuses on manipulation rather than manipulators This attention to processes rather than devices allows a more fundamental approach leading to results that apply to a broad range of devices not just robotic arms The book draws both on classical mechanics and on classical planning which introduces the element of imperfect information The book does not propose a specific solution to the problem of manipulation but rather outlines a path of inquiry *Official Gazette of the United States Patent and Trademark Office* ,2002 *Proceedings of I4SDG Workshop 2025 - IFToMM for Sustainable Development Goals*

Giuseppe Carbone,Giuseppe Quaglia,2025-05-21 This book contains the proceedings of the 3rd IFToMM Workshop for Sustainable Development Goals I4SDG held in Lamezia Terme Italy on June 9 11 2025 The workshop papers are focused on those aspects of the theory design and applications of mechanism and machine science that are fundamental for moving toward sustainable development The main topics of the workshop are sustainable energy systems robotics and mechatronics biomechanical and medical systems education linkages gears transmissions and actuators engines and powertrains tribology transportation machinery service systems for sustainability humanitarian engineering and socio technical systems for

sustainable and inclusive development The contributions selected through a rigorous international peer review process highlight many exciting ideas that will drive new research directions and foster multidisciplinary collaboration between researchers from different backgrounds

DSmT Decision-Making Algorithms for Finding Grasping Configurations of Robot Dexterous Hands Ionel-Alexandru Gal, Danut Bucur, Luige Vladareanu, In this paper we present a deciding technique for robotic dexterous hand configurations This algorithm can be used to decide on how to configure a robotic hand so it can grasp objects in different scenarios Receiving as input several sensor signals that provide information on the object s shape the DSmT decision making algorithm passes the information through several steps before deciding what hand configuration should be used for a certain object and task

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