

ROBOTICS AND AUTOMATION

UNIT 1 – BASIC CONCEPTS PART – A

1. Define a Robot? (Apr 2014)

RIA defines a robot as a “programmable, multifunction manipulator designed to Move materials, parts, tools or special devices through variable programmed motions for the performance of the variety of task”.

2. What is meant by automation and what are its types?

Automation is a technology that is concerned with the use of electronic mechanical and computer based system in the operation control and production.

Various types of automation:

- Fixed automation
- Programmable automation
- Flexible automation

3. Why a robot used?

- a. To reduce production cost
 - Fast
 - Accurate
 - Difficulties in human nature
- b. To avoid 3-D jobs
 - Dirty
 - Dangerous
 - Difficult

4. What is meant by robot anatomy?(Nov 2013)

Robot anatomy means study of structure of robot. Manipulator is constructed of a series of joints & links. A joint provides relative motion between the input link and the output link. Each joint provides the robot with one degree of freedom.

5. Write are the Benefits of industrial automation? (Apr 2014)

- Improved product quality
- Improved safety
- Increased manufacturing flexibility
- Improved operation reliability
- Improved decision making

6. Write Asimov's laws of robotics?(Nov 2013)

Three rules written by science fiction author Isaac Asimov and later expanded upon. These rules are built in to almost all positronic robots appearing in his fiction and cannot be bypassed. The rules are introduced in his 1942 short story Runaround although they were foreshadowed in a few earlier stories.

The Three Laws of Robotics are as follows:

- I. A robot may not injure a human being or, through inaction, allow a human being to come to harm.
- II. A robot must obey any orders given to it by human beings, except where such orders would conflict with the First Law.
- III. A robot must protect its own existence as long as such protection does not conflict with the First or Second Law.

7. Classify the motion control of Robot arm?

- Limited sequence control
- Point to point control
- Continuous path control
- Intelligent control

Objective Question Bank Automation And Industrial Robotics

Chetan Sandhu



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Conference on Robotics in Alpe Adria Danube Region RAAD 2019 held at the Fraunhofer Zentrum and the Technische Universität in Kaiserslautern Germany on 19-21 June 2019. The conference brought together academic researchers in robotics from 20 countries mainly affiliated to the Alpe Adria Danube Region and covered all major areas of robotic research development and innovation as well as new applications and current trends. Offering a comprehensive overview of the ongoing research in the field of robotics, the book is a source of information and inspiration for researchers wanting to improve their work and gather new ideas for future developments. It also provides researchers with an innovative and up-to-date perspective on the state of the art in this area. *Advances in Manufacturing Technology XXXIII* Mark Price, 2019-08-15

The development and management of technologies and operations are key to the success of all types of manufacturing business. This book presents the proceedings of the 17th International Conference on Manufacturing Research ICMR 2019 held in Belfast UK on 10-12 September 2019. ICMR has been the UK's main manufacturing research conference for 34 years and an international conference since 2003. It brings together researchers, academics, and industrialists to share their vision, knowledge, and experience and discuss emerging trends and new challenges in manufacturing research. The conference theme of ICMR2019 was smart manufacturing, and the book includes the 82 papers presented at the conference representing an acceptance rate of 69%. These have been divided into 13 parts which cover topics ranging from robot automation and machining processes, additive manufacturing, composite manufacturing, design methods, to information management, quality control, production optimization, and product lifecycle management. Providing an overview of current trends and developments, the book will be of interest to researchers and engineers in the relevant area of manufacturing processes design and production management. **Multi-Agent Systems** Vadim Malvone, Aniello Murano, 2023-09-06

This volume LNCS 14282 constitutes the refereed proceedings of the 20th European Conference EUMAS 2023 held in Naples, Italy, during September 2023. This volume includes 24 full papers and 5 short papers carefully selected from 47 submissions. Additionally, the volume features 16 short papers rigorously reviewed from 20 submissions for the PhD day. The conference focused on the theory and practice of autonomous agents and multi-agent systems covering a wide range of topics. NASA SP-7500 United States. National Aeronautics and Space Administration, 1982

Mechatronics '98 J. Adolfsson, J. Karlén, 1998-08-28

Mechatronics, a synergistic combination of mechanical, electronic, and computing engineering technologies, is a truly multidisciplinary approach to engineering. New products based on mechatronic principles are demonstrating reduced mechanical complexity, increased performance, and often previously impossible capabilities. This book contains the papers presented at the UK Mechatronics Forum's 6th International Conference held in Skövde, Sweden, in September 1998. Many of these high-quality papers illustrate the tremendous influence of mechatronics on such areas as manufacturing machinery, automotive engineering, textiles manufacture, robotics, and real-time control and vision systems. There are also papers describing developments in sensors, actuators, control, and data processing techniques such as fuzzy logic and neural

networks all of which have practical application to mechatronic systems Proceedings of the 2nd Conference on Industrial Robot Technology, University of Birmingham, U. K., March 27th-29th, 1974 ; Edited by T. E. Brock and Wendy A. Thornton University of Nottingham. Department of Production Engineering and Production Management,1974 *Modern Problems of Robotics* Arkady Yuschenko,2021-10-08 This book constitutes the post conference proceedings of the 2nd International Conference on Modern Problems of Robotics MPoR 2020 held in Moscow Russia in March 2020 The 16 revised full papers were carefully reviewed and selected from 21 submissions The volume includes the following topical sections Collaborative Robotic Systems Robotic Systems Design and Simulation and Robots Control The papers are devoted to the most interesting today s investigations in Robotics such as the problems of the human robot interaction the problems of robot design and simulation and the problems of robot and robotic complexes control *Management* ,1986 Realising CIM's Industrial Potential C. Kooij,P. MacConaill,J. Bastos,1993 The CIM Europe provides a focal point for reporting on progress in Computer Integrated Manufacturing CIM CIM practitioners decision makers and researchers exchange experiences gained in developing and implementing CIM technologies This work deals with the application of technology innovation to industrial demand **Continual Improvement: A Bibliography with Indexes, 1992-1993** ,1994 **Digital Human Modeling and Applications in Health, Safety, Ergonomics and Risk Management. Human Body Modeling and Ergonomics** Vincent G. Duffy,2013-06-28 This two volume set LNCS 8025 8026 constitutes the refereed proceedings of the Fourth International Conference on Digital Human Modeling and Applications in Health Safety Ergonomics and Risk Management formerly International Conference on Digital Human Modeling DHM 2013 held as part of the 15th International Conference on Human Computer Interaction HCII 2013 held in Las Vegas USA in July 2013 jointly with 12 other thematically similar conferences The total of 1666 papers and 303 posters presented at the HCII 2013 conferences was carefully reviewed and selected from 5210 submissions These papers address the latest research and development efforts and highlight the human aspects of design and use of computing systems The papers accepted for presentation thoroughly cover the entire field of Human Computer Interaction addressing major advances in knowledge and effective use of computers in a variety of application areas This two volume set contains 91 papers The papers in this volume focus on the following topics digital human modeling and ergonomics in working environments ergonomics of work with computers anthropometry posture and motion modeling The Industrial Robot ,1980 **Resources in Education** ,1995-07

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