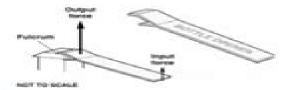
Physical Science - Chapter 14 Review Sheet

- 1. When does a force applied to an object not do any work? When there is no displacement
- 2. What is the unit of work? Joule
- If you exert a force of 10.0 N to lift a box a distance of 0.75 m, how much work do you do? 7.5.
- If you perform 30 joules of work lifting a 20-N box from the floor to a shelf, how high is the shelf? 1.5 m
- 5. The SI unit of power is the ______ Watt
- If you exert a force of 500 N to walk 4 m up a flight of stairs in 4 s, how much power do you use? 500 W
- 7. A machine is a device that can multiply . Force
- When a machine does work, it can do all of the following EXCEPT
 - a. change the direction of a force.
 - increase a force and change the distance a force moves.
 - increase the distance a force moves and change the direction of a force.
 - d. increase a force and increase the distance a force moves.
- 9. If you know the input distance and output distance of a machine, which of the following can you calculate? ****
- If you have to apply 30 N of force on a crowbar to lift an rock that weights 330 N, what is the actual mechanical advantage of the crowbar?
- 11. The efficiency of a machine is always less than 100 percent because _______ of friction
- A motor with an efficiency rating of 80 percent must supply 300 J of useful work. What amount of work must be supplied to the motor? 375 J
- 13. Which of the following is an example of a wheel and axie?
 - a. a doorknob
 - an automobile steering wheel

- c. a jar lid
 d. a pencil
- 14. The rate at which work is done is called _______power
- The force that is exerted on a machine is called the force. Output force.
- 17. The fulcrum is always between the effort force and the resistance force in a(an) -class lever. 5781
- Compare the size and direction of the input and output forces shown in the figure to the right. Same direction, output force is greater
- The ideal mechanical advantage of a third-class lever is always than 1. less
- If you grease a ramp to make a box slide more easily, what happens to the ramp's mechanical advantage? increases
- 22. If a simple machine could be frictionless, how would its IMA and AMA compare? equal
- 23. How does friction affect the calculation of the IMA of a simple machine? it doesn't
- The input force of a pulley system must move 6.0 m to lift a 3000-N engine a distance of 0.50 m. What is the IMA of the system?
- 25. A force of 12 N is applied to the handle of a screwdriver being used to pry off the lid of a paint can. As the force moves through a distance 0.3 m, the screwdriver does 32 J of work on the lid. What is the efficiency of the screwdriver? BAD QUESTION
- 26. What is the IMA of the ramp in the figure at the right? 3





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Clifford Lane

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in a solid aluminum frame and equipped with a planetary ... SRV02 Position Control using QuaRC This laboratory guide contains pre-lab and in-lab exercises demonstrating how to design and implement a position controller on the Quanser SRV02 rotary ... Quanser SRV02 Workbook Jan 1, 2019 — Hakan Gurocak, Washington State University Vancouver, USA, for rewriting this manual to include embedded outcomes assessment. SRV02 Workbook - ... SRV02 User Manual SRV02 User Manual 1. Presentation. 1.1. Description. The Quanser SRV02 rotary servo plant, pictured in Figure 1, consists of a DC motor that is encased in a. Quanser SRV02 Workbook Jan 1, 2019 — SRV02 Manual (Student).pdf. This laboratory guide contains pre-lab questions and lab experiments demonstrating how to model the Quanser. SRV02 ... SRV02 User Manual This module is designed to mount to a Quanser rotary servo plant (SRV02). The sensor shaft is aligned with the motor shaft. One end of a rigid link is mounted ... SRV02_Rotary Pendulum_User Manual.sxw The following table describes the typical setup using the complete Quanser solution. It is assumed that the ROTPEN is being used along with an SRV02, UPM and Q8 ... SRV02 Gyroscope User Manual The Quanser SRV02 and gyroscope system provides a great platform to study gyroscope properties along with control experiments that resemble real-life ... Rotary Servo Base Unit The Rotary Servo Base Unit is the fundamental element of the Quanser Rotary Control family. It is ideally suited to introduce basic control concepts and ... Control Systems Lab Solutions Quansers lab equipment for control systems are precise, robust, open architecture solutions for a wide range of teaching and research applications.