

## **PROJECT MANAGEMENT PLAN**

### **Document Purpose**

The purpose of this document is to provide guidance on the practice of developing a **Project Management Plan** and to describe the practice overview, requirements, best practices, activities, and key terms related to these requirements. In addition, templates relevant to this practice are provided at the end of this guide.

### **Practice Overview**

Project Management Institute (PMI) Project Management Body of Knowledge (PMBOK) defines a Project Management Plan (PMP) as a formal approved document that defines the overall plan for how the project will be executed, monitored and controlled.

The PMP may be a single detailed document or composed of one or more subsidiary planning documents. These additional planning documents provide guidance and direction for specific management, planning, and control activities such as schedule, cost, risk, staffing, change control, communication, quality, procurement, deployment, etc. Each of the subsidiary planning documents should be detailed to the extent required by the specific project.

A PMP is essential for defining how project integration management will be executed when situations arise where individual processes interact. For example, estimating cost involves not only the cost management process but also integration of planning, time, risk, scope etc.

Project Management Institute (PMI) Project Management Body of Knowledge (PMBOK) defines Project Integration Management as the processes and activities needed to identify, define, combine, unify, and coordinate the various processes and project management activities.

In context of project management, integration includes characteristics of unification and consolidation actions necessary for project completion. Integration management also involves making trade-offs among competing objectives and alternatives. Integration in the context of managing a project is making choices about where to concentrate resources and effort on any given day, anticipating potential issues, dealing with these issues before they become critical, and coordinating work. A properly developed PMP outlines how these activities will be conducted taking into consideration any effect they may have on each other and other management processes and/or activities. As the project environment changes updates in the form of change requests should reflect any changes to the PMP and/or its subsidiary plans.

# Sample Project Management Plan Document

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a four quadrant or multiple quadrant operation is required in industrial as well as commercial applications these applications require both driving and braking i e motoring and generating capability some of these applications include electric traction systems cranes and lifts cable laying winders and engine test loading systems

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speed control of a machine is the most vital and important part in any industrial organization this paper is designed to develop a four quadrant speed control system for a dc motor using microcontroller the motor is operated in four quadrants i e clockwise counter clock wise forward brake and reverse brake

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paper proposes a way to govern the rate and route control of a dc motor with the help of a 4 quadrant dc dc chopper the speed under the base velocity may be controlled by way of armature voltage manage technique mosfets are used for the switching operation of the chopper the gates of those mosfets are given pwm

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the four quadrant chopper block represents a four quadrant controlled chopper for converting a fixed dc input to a variable dc output the block contains two bridge arms each bridge arm each has two switching devices options for the type of

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3 four quadrant operation of dc motor four quadrant operation or mode of any dc motor means that machine operate in four

quadrants they are forward braking mode forward motoring mode reverse braking or stop mode and reverse motoring mode a motor operates in two modes motoring and braking a motor drive capable of

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this paper gives a control for three phase brushless dc bldc motor in all four quadrant operation the control system in this paper is capable to detect and identify the rotor position by sensor signal 1 in this paper behaviour of bldc motor is studied in all four quadrant operations through simulation model

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may 11 2021 a four quadrants dc chopper fqdc has been developed to work with a series motor for the application of dc drive electric vehicle in previous work capable of operating in such driving conditions and offers several types of chopper operation modes such as driving and reverse regenerative and resistive braking generator mode field weakening

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aug 8 2020 1 answer sorted by 1 you can think of the first quadrant operation as being a buck converter down from the supply to the motor you can think of the second quadrant as being a boost converter from the motor s generated low voltage up to the supply voltage

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put simply the four quadrants that the controller can work in are 1 motor going clockwise controller applying clockwise drive 2 motor going anti clockwise controller applying anti clockwise drive 3 motor going clockwise controller applying anti clockwise drive 4 motor going anti clockwise controller applying clockwise drive

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sep 11 2019 four quadrants drive dc chopper for series motor full size image this modes of operation can be controlled by ai controllers such as expert system fuzzy logic self tuning fuzzy 10 11 12 13 14 15 16 neural network as well as anfis but this paper focused only on the circuit operation of generator mode

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four quadrant operation of dc motor means that the machine operates in four quadrants they are forward braking forward motoring reverse motoring and reverse braking a motor operates in two modes motoring and braking

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1 to observe the four quadrant operation of a dc motor 2 to control a motor under torque control 3 to couple the speed

control motor and torque controlled motor and observe the effect of a stepped torque 6 2 four quadrant operation of a dc motor the four quadrant operation is performed by giving an alternating reference speed command to

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aug 16 2021 the four quadrant operation of the motor can be described as follows quadrant i in the first quadrant the developed power by the motor is positive thus the motor operates in motoring mode and converts electrical energy into mechanical energy therefore the operation of the motor in first quadrant is called forward motoring quadrant ii

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the control of bldc motor in four quadrants is very crucial in this paper bldc motor is controlled in all the four quadrants without any wastage of power during regenerative braking period power generated is being stored in the chargeable battery

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aug 3 2019 introduction in this experiment four quadrant operation of a dc motor is simulated as well as run in real time the speed and current control model developed in the previous experiment is used to emulate the four regions of operation theoretical background consider an elevator system shown in figure below

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four quadrant operation of a pm dc motor 5 1 objective the objective of this activity is to analyze the four quadrant operation of a permanent magnet dc pm dc motor this activity was derived from those developed and distributed by the university of minnesota umn 5 2 review of four quadrant operation

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jan 1 2020 2020 public holidays michigan service the above is the list of 2020 public holidays declared in michigan which includes federal regional government holidays and popular observances we also provide michigan holiday calendar for 2020 in word excel pdf and printable online formats

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web projectile motion is an example of motion with constant acceleration in this experiment a projectile will be fired from some height above the floor and the position where it lands will be predicted to make this prediction one needs to know how to describe the motion of the projectile using the laws of physics the

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web the purpose of this lab is to study the motion of a projectile launched using a projectile launcher and inspect different aspects of projectile motion using highspeed video processing sample results trajectory of the projectile curve fitting for vertical velocity visualisation of the trajectory of the projectile total energy time vs height

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web projectile motion launching a ball the purpose of this lab experiment was to observe an object moving in a projectile pathway and analyze this motion through measurements taken and found the objective of this lab experiment was to visualize a ball launched in a projectile pathway

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web in this experiment you will use video analysis techniques to obtain position velocity and time data for a projectile analyze the position vs time and velocity vs time graphs for both the horizontal and vertical components of the projectile s motion

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web lab 4 projectile motion goals to determine the launch speed of a projectile and its uncertainty by measuring how far it travels horizontally before landing on the floor called the range when launched horizontally from a known height to predict and measure the range of a projectile when the projectile is fired at an arbitrary

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web projectile motion is the motion of an object thrown projected into the air when after the initial force that launches the object air resistance is negligible and the only other force that object experiences is the force of gravity

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web this projectile simulator allows students to alter the launch speed launch height and launch angle of a projectile the trajectory range and time of flight are displayed the velocity vector components acceleration vector and the trajectory trace can be toggled off and on

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web projectile motion is a form of motion where an object moves in a parabolic path the path followed by the object is called its trajectory projectile motion occurs when a force is applied at the beginning of the trajectory for the launch after this the projectile is subject only to the gravity

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web what is projectile motion find the initial velocity  $v_0$  of a ball rolling off the table in the figure below the launch position is the origin of the coordinate system positive directions as specified

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web sep 26 2020 this activity is a lab experiment about projectile motion designed for physics 1 remote learning students it uses phet projectile motion simulation to give the students the ability to distinguish the relation of the initial speed of the projectile and other physical quantities

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web projectile motion lab introduction projectile motion is a path traveled by an object influenced by the initial velocity launch angle and the acceleration due to gravity in this experiment you will predict the spot a steel ball will land after being launched objectives in this experiment you will

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web free fall motion lab report 7 lab 6 12 4 18 by applying known torques to a system which is free to rotate the resulting impulse and momentum in collisions lab report motion in free fall lab report period of oscillating ring lab report ai quiz save projectile motion lab report

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web nov 14 2023 projectile motion projectile is defined as any body thrown with some initial velocity which is then allowed to move under the action of gravity alone without being propelled by any engine or fuel the path followed by a projectile is called its trajectory

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web in this lab we will study two dimensional projectile motion of an object in free fall that is an object that is launched into the air and then moves under the influence of gravity alone examples of projectiles include rockets baseballs reworks and the steel balls that will be used in this lab

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web projectile motion is the motion of an object thrown or projected into the air subject only to acceleration as a result of gravity the applications of projectile motion in physics and engineering are numerous some examples include meteors as they enter earth's atmosphere fireworks and the motion of any ball in sports

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web nov 15 2023 after clicking the fire button the user can view the motion of the projectile and also the time of flight maximum height and range of the projectile variable region the choose environment combo box helps you to choose the type of environment that the simulation has to be performed

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web the purpose of this experiment is to describe projectile motion the measured physical quantities that are measured in this experiment include length meter and time second s the physical quantities that will be calculated based on those measurements include speed horizontal motion vertical motion and overall velocity

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web blast a car out of a cannon and challenge yourself to hit a target learn about projectile motion by firing various objects set parameters such as angle initial speed and mass explore vector representations and add air resistance to