Planar Multibod **Dynamics**

Formulation, **Programming** with MATLAB, and Applications 0.013 0.015 k, L 0, d c, f a) "f A1: n2 = s rot(s B2)" f

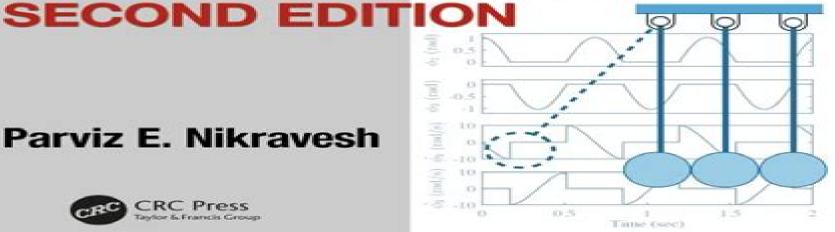
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's A1 local; s B2 = A2's B2 lc

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Parviz E. Nikravesh





Planar Multibody Dynamics Formulation Applications

Jean-Claude Samin, Paul Fisette

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