#### 0.1: Physical Constants

	10 40 4 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
(C)	$3 \times 10^8 \text{ m/s}$
- Ai	$6.63 \times 10^{-34} \text{ J/s}$
he	1242 eV-nm
-G	$6.67 \times 10^{-11} \text{ m}^3 \text{ kg}^{-1} \text{ s}^{-2}$
- Ac	$1.38 \times 10^{-23} \text{ J/K}$
R	8.314 J/(mol K)
$-N_{A}$	$6.023 \times 10^{23} \text{ mol}^{-1}$
- 6	$1.602 \times 10^{-19} \text{ C}$
Mo	$4\pi \times 10^{-7} \text{ N/A}^2$
0.00000	
$-\epsilon_0$	$8.85 \times 10^{-12} \text{ F/m}$
Arres .	$9 \times 10^9 \text{ N m}^2/\text{C}^2$
F	96485 C/mol
700.0	$9.1 \times 10^{-31} \text{ kg}$
993 p	$1.6726 \times 10^{-27} \text{ kg}$
Tri <sub>m</sub>	$1.6749 \times 10^{-27} \text{ kg}$
846	$1.66 \times 10^{-27} \text{ kg}$
100	931.49 MeV/c <sup>2</sup>
er.	$5.67 \times 10^{-8} \text{ W/(m}^2 \text{ K}^4)$
$R_{\infty}$	$1.097 \times 10^{7} \text{ m}^{-1}$
$\mu a$	$9.27 \times 10^{-24} \text{ J/T}$
dia	$0.529 \times 10^{-10} \text{ m}$
attm	$1.01325 \times 10^{5} \text{ Pa}$
6	$2.9\times10^{-3}~\mathrm{m~K}$
	$h$ $hc$ $G$ $k$ $R$ $N_A$ $e$ $\mu_0$ $e_0$ $\frac{1}{4\pi\epsilon_0}$ $F$ $m_p$ $m_n$ $u$ $\sigma$ $R_\infty$ $\mu_B$ $a_0$ $a_0$

#### 1 MECHANICS

#### 1.1: Vectors

Notation:  $\vec{a} = a_x \, i + a_y \, j + a_z \, \hat{k}$ 

Magnitude:  $a = |\vec{a}| = \sqrt{a_x^2 + a_y^2 + a_z^2}$ 

Dot product:  $\vec{a} \cdot \vec{b} = a_x b_x + a_y b_y + a_z b_z = ab \cos \theta$ 

Cross product:

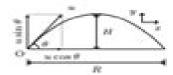


#### Motion in a straight line with constant a:

$$v=u+at, \quad s=ut+\tfrac{1}{2}at^2, \quad v^2-u^2=2as$$

Relative Velocity: 
$$\vec{v}_{A/B} = \vec{v}_A - \vec{v}_B$$

#### Projectile Motion:



$$x = ut \cos \theta$$
,  $y = ut \sin \theta - \frac{1}{2}gt^2$   
 $y = x \tan \theta - \frac{g}{2u^2 \cos^2 \theta}x^2$ 

$$T = \frac{2u \sin \theta}{g}$$
,  $R = \frac{u^2 \sin 2\theta}{g}$ ,  $H = \frac{u^2 \sin^2 \theta}{2g}$ 

#### 1.3: Newton's Laws and Friction

Linear momentum:  $\vec{p} = m\vec{v}$ 

Newton's first law: inertial frame.

Newton's second law:  $\vec{F} = \frac{d\vec{F}}{dt}$ ,  $\vec{F} = m\vec{a}$ 

Newton's third law:  $\vec{F}_{AB} = -\vec{F}_{BA}$ 

Frictional force:  $f_{\text{static, max}} = \mu_s N$ ,  $f_{\text{kinetic}} = \mu_k N$ 

Banking angle:  $\frac{v^2}{rg} = \tan \theta$ ,  $\frac{v^2}{rg} = \frac{\mu + \tan \theta}{1 - \mu \tan \theta}$ 

Centripetal force:  $F_c = \frac{mv^2}{r}$ ,  $a_c = \frac{v^2}{r}$ 

Pseudo force:  $\vec{F}_{pseudo} = -m\vec{a}_0$ ,  $F_{centrifugal} = -\frac{m\pi^2}{c}$ 

Minimum speed to complete vertical circle:

$$v_{\text{min, bottom}} = \sqrt{5gl}$$
,  $v_{\text{min, top}} = \sqrt{gl}$ 

# Conical pendulum: $T = 2\pi \sqrt{\frac{f \cos \theta}{\theta}}$

4 4 444 4



# **Neet Physics Formula**

**TD Snyder** 

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