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Handbook of Research on Using Educational Robotics to Facilitate Student Learning Papadakis, Stamatios, Kalogiannakis, Michail, 2020-12-05 Over the last few years increasing attention has been focused on the development of children's acquisition of 21st century skills and digital competences. Consequently many education scholars have argued that teaching technology to young children is vital in keeping up with 21st century employment patterns. Technologies such as those that involve robotics or coding apps come at a time when the demand for computing jobs around the globe is at an all time high while its supply is at an all time low. There is no doubt that coding with robotics is a wonderful tool for learners of all ages as it provides a catalyst to introduce them to computational thinking, algorithmic thinking and project management. Additionally recent studies argue that the use of a developmentally appropriate robotics curriculum can help to change negative stereotypes and ideas children may initially have about technology and engineering. The Handbook of Research on Using Educational Robotics to Facilitate Student Learning is an edited book that advocates for a new approach to computational thinking and computing education with the use of educational robotics and coding apps. The book argues that while learning about computing young people should also have opportunities to create with computing which have a direct impact on their lives and their communities. It develops two key dimensions for understanding and developing educational experiences that support students in engaging in computational action: 1 computational identity which shows the importance of young people's development of scientific identity for future STEM growth and 2 digital empowerment to instill the belief that they can put their computational identity into action in authentic and meaningful ways. Covering subthemes including student competency and assessment, programming education and teacher and mentor development, this book is ideal for teachers, instructional designers, educational technology developers, school administrators, academicians, researchers and students.

Advances in Robots Technologies and Implementations Dina Darwish, In Czech the word robota means serf work which is where the name robot originates from a drama written by Karel Capek in 1920 in which machines take control of the world is credited for popularizing the term robot. However the rethinking of human life has always been something that mankind has been interested in. Ever since the beginning of the 20th century there have been several attempts to rebuild a human person and there are stories that tell of those who have been successful before Paracelsus an alchemist who lived in the 16th century is credited with having one of the most well known theories. He asserted that a miniature human like entity which he referred to as a homunculus could be made in a flask by doing nothing more than employing chemical processes. In the latter part of the 16th century the term golem became well known to the general population. In accordance with a traditional tale the golem was constructed out of clay and had the ability to provide assistance to anyone if a unique paper was put into either its mouth or its forehead. According to the narrative the golem ultimately met its creator and eventually turned against him. This occurred after some time had passed. When one considers the history of robotics one discovers that

there is a widespread interest in endowing robots with humanity or elements that are characteristic of humans. In general, there are primary criteria which are as follows: The robot must be able to resemble a human being in some manner in terms of look, thinking, and personality, for example. The robot needs to be superior in some way that is, it needs to be stronger, smarter, etc. This means that the designer of the robot must have full control over the robot themselves. When it came to the history of robotics, a significant turning point occurred when robots that were more powerful than people were created. It was about the year 1769 when the first industrial revolution began, and it was around this time that machines began to supplant the human input to labor. During that time period, the primary objective was to increase the number of products as well as decrease the amount of time and money spent on manufacturing, all without involving any human intervention. At that point in time, automation emerged as the most common notion. Automation allows for the completion of several procedures without the need for any involvement from a human being. People were forced to come up with new methods of working and living as a result of humans being replaced by robots. Machines are able to operate around the clock because they do not experience fatigue in the same way that people do. Automation led to a reduction in both the likelihood of making mistakes and the quantity of waste produced. In addition, robots are distinguished by their regulated precision and their enhanced efficiency. It was not possible to have access to computer technology in the 1800s. Nevertheless, mankind was able to construct gigantic machines that were capable of carrying out difficult jobs. Following the year 1950, there has been a significant advancement in the field of robots. The discovery of the moon's surface by the first mobile robot that was operated remotely, which occurred around the year 1970, is another significant event in the history of robotics. Later on, in 1986, Honda initiated a project with the intention of developing humanoid robots that have a similar appearance to that of humans. Robots began to appear in an increasing number of industries, including healthcare, manufacturing, and logistics, as the progress of the technology continued. In spite of the fact that the development of robots is still in progress, we can already find robots in our everyday life. For example, robots can be found in the household in the form of vacuum cleaners, in the office in the form of assembly robots, and in the medical field in the form of social robots in patient therapy or surgical robots. This is the fourth industrial revolution that humanity is now experiencing. This revolution is integrating the most cutting-edge developing technologies, such as robots, internet of things, fifth generation wireless networks, artificial intelligence, and many others, in order to propel the industry to new heights. There are several categories that may be applied to robots. We will examine the following four primary approaches to classification: Size, Application domain, Purpose, and Number of users per application. When considering dimensions, the following categories can be distinguished. Nanorobots, also known as nanobots, are constructed out of nanomaterials and can range in size from 0.1 to 10 micrometers. To give you an idea of how little these nanorobots are, a human red blood cell is around 5-10 micrometers in size. The notion of nanobots is now in the preliminary phases of study; primarily, it is being considered for its potential application in the medical field. It will take many more years of laborious

effort to make nanobots a viable answer Injecting nanorobots into the body of a patient in order to diagnose and treat illnesses is one of the potential applications of nanorobots Microrobots millibots and minibots are all examples of robots that are significantly bigger than nanobots These robots are already in existence Microbots millibots and minibots are correspondingly smaller than one millimeter one centimeter and ten centimeters RoboBee which has a wingspan of 1.2 centimeters and weighs 80 milligrams is the smallest flying robot that has ever been created A remote control can be used to operate the robot and its wings have the ability to flap 120 times per second The purpose of such a little apparatus is to create a flying swarm for the purpose of artificial pollination or search and rescue operations Robots that are little and medium sized these robots are often less than 100 centimeters small or almost the same size as a human being mid sized 100-200 centimeters This is the size of the majority of robots that are used in homes toys and social robots humanoids robots that have an appearance that is comparable to that of humans the Transformers from comic books and movies are a typical example and digital personal assistants The majority of the time whether in movies or in real life we encounter and interact with robots that are of both small and medium size Huge robots these machines are far larger than we are Some humanoid robots are rather enormous reaching heights of up to eight to ten meters However humanoid big robots are often constructed for the aim of study or just for the goal of having fun As a matter of fact the majority of huge robots do not resemble people rather they are designed to automate various tasks such as manufacturing construction agriculture autonomous driving and navigation Robots may also be classified according to the application domain in which they are used with personal robots and industrial robots being the two categories that can be achieved Robots that are meant to be beneficial for individuals or families are employed in our everyday lives and are referred to as personal robots Personal robots can be operated by those who are not technically savvy to carry out duties that are repetitive and possibly monotonous in order to save time or to entertain us Among the various types of personal robots the most frequent types are social robots digital personal assistants toys and household robots Robots designed for use in manufacturing construction or agriculture for example are built to withstand harsh conditions and are designed to carry out certain duties in accordance with a predetermined set of instructions Assembly disassembly mounting screw tightening welding painting visual inspection and other applications are just some of the many uses for this tool There is one particular activity that industrial robots excel at and that is working as machines that are quick accurate and dependable We would not be able to achieve the degree of technical growth that we have today if it were not for industrial robots The function of robots is yet another classification that might be chosen Both particular and generic functions are possible for robots to do So what exactly does that imply Task specific robots these machines are designed to carry out a single task or a series of activities that might be performed independently Depending on the level of complexity it might be as straightforward as a robot arm that transports things from point A to point B or it could be as intricate as a social robot that has an advanced natural language interface The architecture and conduct of these

robots cannot be altered they have predetermined programming that they follow in accordance with the purpose for which they were established These types of devices include industrial robots as well as robots used in households General purpose robots When it comes to general purpose robotics the task that the robot is supposed to perform is not predetermined There are a variety of components of the robots that can be purchased individually and these components may be joined in a variety of different ways in order to accomplish certain projects There is a possibility that the components will consist of robot arms wheels cameras step motors and more sensors and actuators Another possibility is that these robots are equipped with wireless connections such as Bluetooth and Wi Fi The brain of the robot which is often a tiny computer may be trained to carry out a variety of activities using a variety of components by utilizing specialized programs that are written in computer programming languages The Nvidia Jetson and Jetson Nano Raspberry Pi and Arduino are examples of popular programmable tiny computers which are often referred to as embedded systems Through the use of a common communication interface these embedded systems are equipped with general purpose input and output connectors often known as GPIOs These connections allow for the connecting of actuators and sensors There are also general purpose robots that have a prebuilt body that is comprised of sensors such as cameras and microphones and actuators such as arms and legs It is possible for the robot to carry out a variety of distinct duties thanks to the development of various computer programs Among the robots that fall under this category are Softbank Robotics Nao Pepper and Romeo as well as Spot the robot dog that Boston Dynamics has developed In addition robots can be classified according to the number of instances of each type Single robots a single robot accomplishes its tasks independently It is responsible for carrying out a task in accordance with a predetermined program It is possible that the established program may incorporate cutting edge technologies that will enable the robot to adjust to its surroundings Additionally the robot may be connected to the internet yet the robot will still be operating independently Due to the fact that they are unable to interact with one another even if there are many single robots in the same location they are still considered to be alone Swarm robots robots are able to collaborate with one another in a group setting Within the context of this scenario a large number of simple robots are controlled and collaborate with one another Despite the fact that the individual robots that comprise the swarm are not particularly useful the swarm as a whole is capable of doing substantial tasks Take for instance bees that are found in their natural habitat If millions of bees were to collaborate in swarms it is quite possible that they accomplish huge tasks This is because a single bee is only capable of accomplishing a small amount of work There is the possibility that swarm robots could be utilized in a wide range of sectors such as microbiology surveillance pollination as well as exploration and rescue Despite this the vast bulk of research on swarm robots is still being carried out at the time that this book is being presented Nevertheless an additional cause for concern arises whenever the degree of realism of robots is increased Individuals are typically receptive to robots that are designed to mimic humans In the same way that we identify industrial robots in the manufacturing industry our brain is able

to quickly categorize humanoid robots that resemble robots This is similar to how we classified industrial robots It is possible for individuals to suffer uncertainty and even frustration when they come into contact with a robot that is artificially lifelike We are aware that it is a robot given the facts that have transpired However the brain is unable to deal with this reality since it seems to be so accurate This is because the brain is unable to process the information Despite the fact that its skin movement and even voice are strikingly similar to those of a person our brain has a difficult time recognizing it as a robot This book provides a good beginning for people interested in knowing more information about robots and includes several chapters ranging from robots main concepts robots functioning basics advances in robotics technologies and implementations robots in education and advanced topics in robotics

Handbook of Research on Advancements in Robotics and Mechatronics Habib, Maki K.,2014-12-31 The field of mechatronics integrates modern engineering science and technologies with new ways of thinking enhancing the design of products and manufacturing processes This synergy enables the creation and evolution of new intelligent human oriented machines The Handbook of Research on Advancements in Robotics and Mechatronics presents new findings practices technological innovations and theoretical perspectives on the the latest advancements in the field of mechanical engineering This book is of great use to engineers and scientists students researchers and practitioners looking to develop autonomous and smart products and systems for meeting today s challenges

Smart Learning with Educational Robotics Linda Daniela,2019-06-28 This book will offer ideas on how robots can be used as teachers assistants to scaffold learning outcomes where the robot is a learning agent in self directed learning who can contribute to the development of key competences for today s world through targeted learning such as engineering thinking math physics computational thinking etc starting from pre school and continuing to a higher education level Robotization is speeding up at the moment in a variety of dimensions both through the automation of work by performing intellectual duties and by providing support for people in everyday situations There is increasing political attention especially in Europe on educational systems not being able to keep up with such emerging technologies and efforts to rectify this This edited volume responds to this attention and seeks to explore which pedagogical and educational concepts should be included in the learning process so that the use of robots is meaningful from the pointof view of knowledge construction and so that it is safe from the technological and cybersecurity perspective

Modern Robotics Kevin M. Lynch,Frank C. Park,2017-05-25 A modern and unified treatment of the mechanics planning and control of robots suitable for a first course in robotics

STEM, Robotics, Mobile Apps in Early Childhood and Primary Education Stamatios Papadakis,Michail Kalogiannakis,2022-04-21 This book brings together a collection of work from around the world in order to consider effective STEM robotics mobile apps education from a range of perspectives It presents valuable perspectives both practical and theoretical that enrich the current STEM robotics mobile apps education agenda As such the book makes a substantial contribution to the literature and outlines the key challenges in research policy and practice for STEM education from early

childhood through to the first school age education The audience for the book includes college students teachers of young children college and university faculty and professionals from fields other than education who are unified by their commitment to the care and education of young children *Computational Principles of Mobile Robotics* Gregory Dudek, Michael Jenkin, 2010-07-26 An advanced undergraduate graduate text emphasizing computation and algorithms for locomotion sensing and reasoning in mobile robots **Proceedings of the National Conference on Advanced Manufacturing & Robotics, January 10-11, 2004** S. N. Shome, Jhankar Basu, G. P. Sinha, 2004 Contributed papers presented at the conference held at Central Mechanical Engineering Research Institute Durgapur Surgical Robotics Serdar Küçük, 2018-01-04 Robotic technology has increasingly been preferred by the medical professionals since they have been used for several clinical applications Medical robots are preferred since they present better results compared to traditional methods such as smaller incision higher accuracy and lesser recovery time Medical robots can be divided into three progressive generations The first generation robots were originally industrial robots that had been modified for performing medical applications in orthopedics neurosurgery radiology and radiotherapy in the 1980s The second generation robots have been especially developed for executing surgical operations in the 1990s After the 2000s the third generation medical robots have been designed for performing difficult surgical and medical operations From the first approved surgical robot AESOP to the current da Vinci Surgical System there have been several different kinds of surgical robots produced until now Although the history of surgical robots is very short compared to the history of surgery thousands of surgical robots have been installed in hospitals worldwide and hundreds of thousands of people have been treated by these surgical robots Nowadays the achievements of the surgical robotics amaze both medical professionals and the patients It is noteworthy to follow up on the evolution of surgical robotics in the future **Handbook of Research on K-12 Blended and Virtual Learning Through the i²Flex Classroom Model** Avgerinou, Maria D., Pelonis, Peggy, 2021-03-05 Teaching models that focus on blended and virtual learning have become important during the past year and have become integral for the continuance of learning The i Flex classroom model a variation of blended learning allows non interactive teaching activities to take place without teachers direct involvement freeing up time for more meaningful teacher student and student student interactions There is evidence that i Flex leads to increased student engagement and motivation as well as better exploitation of teachers and classroom time leading to the development of higher order cognitive skills as well as study skills for students future needs related to citizenship college and careers The Handbook of Research on K 12 Blended and Virtual Learning Through the i Flex Classroom Model focuses not only on how to design deliver and evaluate courses but also on how to assess teacher performance in a blended i²Flex way at the K12 level The book will discuss the implementation of the i Flex isquareFlex a non traditional learning methodology which integrates internet based delivery of content and instruction with faculty guided student independent learning in combination with face to face classroom instruction aiming at developing

higher order cognitive skills within a flexible learning design framework While highlighting new methods for improving the classroom and learning experience in addition to preparing students for higher education and careers this publication is an essential reference source for pre service and in service teachers researchers administrators educational technology developers and students interested in how the i2Flex model was implemented in classrooms and the effects of this learning model

Handbook of Research on Tools for Teaching Computational Thinking in P-12 Education Kalogiannakis, Michail, Papadakis, Stamatios, 2020-06-26 While the growth of computational thinking has brought new awareness to the importance of computing education it has also created new challenges Many educational initiatives focus solely on the programming aspects such as variables loops conditionals parallelism operators and data handling divorcing computing from real world contexts and applications This decontextualization threatens to make learners believe that they do not need to learn computing as they cannot envision a future in which they will need to use it just as many see math and physics education as unnecessary The Handbook of Research on Tools for Teaching Computational Thinking in P 12 Education is a cutting edge research publication that examines the implementation of computational thinking into school curriculum in order to develop creative problem solving skills and to build a computational identity which will allow for future STEM growth Moreover the book advocates for a new approach to computing education that argues that while learning about computing young people should also have opportunities to create with computing which will have a direct impact on their lives and their communities Featuring a wide range of topics such as assessment digital teaching and educational robotics this book is ideal for academicians instructional designers teachers education professionals administrators researchers and students

Intelligent Educational Robots Stamatios Papadakis, Georgios Lampropoulos, 2024-12-16 This book focuses on recent advances in maker education and in human robot interaction and on the integration of intelligent educational robots IER in P 12 education It covers various topics and trends about the evolution of maker education and the use of IER and artificial intelligence AI in P 12 education This book offers an overview of recent research into the adoption integration advancements and impact of IER and AI in education It helps researchers practitioners professionals and academicians of various scientific disciplines explore and better comprehend the state of the art of maker education AI and IER their advancements impact and future potentials in education

Robotic Mechanical Systems Fundamentals Shridhar Shastri, 2025-02-20 Robotic Mechanical Systems Fundamentals serves as a comprehensive guide to understanding the core principles and technological intricacies of robotic systems in today s rapidly evolving landscape We offer an in depth exploration of the mechanical foundations that drive the design control and functionality of robots making it an essential resource for students researchers and industry professionals Our journey begins with a thorough examination of the fundamental concepts and historical developments that shape robotics Readers will gain insights into the dynamics of robotic systems through the Newton Euler equations paving the way for a deeper understanding of the Lagrange formulation which

offers a powerful framework for analyzing robot motion Focusing on dynamic modeling we provide a detailed look at the mechanisms governing the behavior of manipulators emphasizing the complexities involved in designing and controlling robotic arms Additionally we address control forces and torques highlighting strategies to ensure precision and efficiency in robotic actions With a holistic approach that considers the ethical and societal implications of robotics **Robotic Mechanical Systems Fundamentals** balances theoretical foundations with practical applications making it accessible for beginners and valuable for seasoned professionals Authored by experts our book equips readers to navigate the fascinating world of robotics inspiring a deeper appreciation for the technologies that shape our future

STEM Education with Robotics
Purvee Chauhan,Vikram Kapila,2023-05-11 This book offers a synthesis of research curriculum examples pedagogy models and classroom recommendations for the effective use of robotics in STEM teaching and learning Authors Chauhan and Kapila demonstrate how the use of educational robotics can catalyze and enhance student learning and understanding within the STEM disciplines The book explores the implementation of design based research DBR technological pedagogical and content knowledge TPACK and the 5E instructional model among others Chapters draw on a variety of pedagogical scaffolds to help teachers deploy educational robotics for classroom use including research driven case studies strategies and standards aligned lesson plans from real life settings This book will benefit STEM teachers STEM teacher educators and STEM education researchers

ECGBL 2019 13th European Conference on Game-Based Learning Lars Elbæk,Gunver Majgaard,Andrea Valente,Saifuddin Khalid,2019-10-03 *Handbook of Research on Integrating ICTs in STEAM Education* Xefteris, Stefanos,2022-05-27 Modern society gives great importance to scientific and technological literacy development of 21st century skills and creating individuals who are not passive users of ICT tools but active thinkers and even tinkerers The learning process is thus constantly evolving to facilitate the acquisition of such skills such as setting goals and making evidence based decisions thinking critically and solving problems while efficiently managing time as well as using technology cooperating ethically and communicating effectively STEAM is the approach to learning that uses concepts from natural sciences technology engineering arts and mathematics to foster critical thinking computational and design thinking as well working effectively together mimicking the process followed by scientists The end goal is engaged and motivated students who participate in experiential and inquiry based learning in fun immersive environments that facilitate learning through a creative process The Handbook of Research on Integrating ICTs in STEAM Education includes current research focusing on the development of STEAM and ICT educational practices tools workflows and frames of operation that encourage science skills but also skills related to the arts and humanities such as creativity imagination and reflection on ethical implications Covering topics such as early childhood education machine learning education educational robotics and web based simulations this major reference work is an essential resource for engineers educators of both K 12 and higher education education administration libraries pre service teachers computer scientists researchers and academics

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Journal of Educational Management and Development Studies Ruby B. Brion & Angela L. Reginaldo, Marjielou C. Abinsay, Vanessa Marie M. Aliazas & Elisa N. Chua, John Vincent C. Aliazas, Julie Fe D. Panoy, Anna Liza P. Del Rosario, & Jocelyn V. Madrideo, Michelle C. Gonzales, Edilberto Z. Andal, Delon A. Ching, Magdalena P. Gaffud & Eudora C. Tabo, Jennifer N. Refugia, 2021-09-30 International Journal of Educational Management and Development Studies IJEMDS is an open access refereed journal focused on educational leadership educational management teaching and learning across all disciplines and levels internationalization of education transnational education and societal issues on educational development The field of education has been continuously evolving as influenced by its nature and the societal factors As the journal celebrates the very dynamic and complex nature of education it provides educators and researchers a platform for their research findings This allows researchers to apply multiple designs to describe analyze and evaluate the history current issues and the future direction of education in regional and international contexts **Shaping the Future of Automation**

With Cloud-Enhanced Robotics Gatti, Rathishchandra Ramachandra, Singh, Chandra, 2024-04-26 In a world where automation is quickly becoming a standard a significant challenge arises the need for robots to overcome their inherent limitations in processing power and storage This bottleneck restricts their potential for innovation and collaboration hindering the realization of true autonomous capabilities The burgeoning field of Cloud Robotics promises a revolutionary solution by seamlessly integrating robots with cloud based technologies This integration empowers robots to offload computation tasks tap into vast data resources and engage in real time collaboration with their mechanical counterparts Existing literature often falls short of providing a holistic understanding of the complex interplay between robotics and cloud computing Researchers academics and industry professionals find themselves grappling with fragmented insights hindering their ability to harness the full potential of cloud enhanced robotics The lack of a centralized resource leaves a void impeding progress and innovation in this groundbreaking field Without a roadmap to navigate the challenges and opportunities presented by cloud robotics stakeholders risk being left behind in an era where interdisciplinary collaboration is paramount Enter *Shaping the Future of Automation With Cloud Enhanced Robotics* a beacon of knowledge designed specifically for academics researchers and industry professionals seeking to unlock the transformative power of cloud robotics From fundamental principles to advanced applications each chapter meticulously unravels the intricacies of cloud infrastructure communication protocols data management human robot interaction and more By addressing challenges and proposing solutions this book not only disseminates recent advancements but also equips readers with actionable insights Real world examples and case studies illuminate the practical applications and benefits of cloud enhanced robotics making it an indispensable guide for professionals aiming to implement these innovations in their operations **Trends in Educational Activity in the Field of Mechanism and Machine Theory (2018-2022)** Juan Carlos García Prada, Cristina Castejon, Jose Ignacio Pedrero Moya, 2023-06-10 This book presents content from the Third International Symposium on the Education in

Mechanism and Machine Science ISEMMS 2022 Among others the chapters report on mechanical engineering education mechanism and machine science in the mechanical engineer curricula methodology virtual laboratories and new laws Special attention is given to MMS experiences in Pandemic times The chapters discuss the current problems in MMS education with the aim of providing solutions and identifying appropriate trends for a modern world common vision in the Engineering education field

STEM Education Across the Learning Continuum Amy MacDonald, Lena Danaia, Steve Murphy, 2020-02-18

This is the first comprehensive book to consider STEM education from early childhood through to senior secondary education It approaches STEM as a form of real world problem based education that draws on the knowledge and skills of the science technology engineering and mathematics disciplines Rather than presenting each of the separate disciplines to an equal extent it focuses on STEM researchers perspectives on how their work contributes to effective STEM education in terms of building knowledge skills and engagement Gathering contributions by authors from various countries the book explores effective STEM education from a range of perspectives within the international context Moreover it addresses critical issues in STEM education including transition and trajectories gender rurality socioeconomic status and cultural diversity By doing so it not only shares the current state of knowledge in this field but also offers a source of inspiration for future research

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