

$$\begin{aligned}
 \frac{Z_1}{Z_2} &= \frac{10+2i+15i+3i^2}{5^2-i^2} \longrightarrow 1 \\
 \frac{Z_1}{Z_2} &= \frac{10+17i+3(-1)}{25-(-1)} \longrightarrow 1 \quad \diamond (i^2 = -1) \\
 \frac{Z_1}{Z_2} &= \frac{10+17i-3}{25+1} \\
 \frac{Z_1}{Z_2} &= \frac{7+17i}{26} \\
 \frac{Z_1}{Z_2} &= \frac{7}{26} + \frac{17}{26}i \longrightarrow 1
 \end{aligned}$$

v. If $x = \sqrt{3} - \sqrt{2}$, find the value of $x - \frac{1}{x}$.

Checking Hints:

Total Marks: 4=1+1+1+1

Solution:

$$x = \sqrt{3} - \sqrt{2}$$

$$\frac{1}{x} = \frac{1}{\sqrt{3} - \sqrt{2}}$$

$$\frac{1}{x} = \frac{1}{\sqrt{3} - \sqrt{2}} \times \frac{\sqrt{3} + \sqrt{2}}{\sqrt{3} + \sqrt{2}} \longrightarrow 1$$

$$\frac{1}{x} = \frac{\sqrt{3} + \sqrt{2}}{(\sqrt{3})^2 - (\sqrt{2})^2}$$

$$\frac{1}{x} = \frac{\sqrt{3} + \sqrt{2}}{3 - 2}$$

1

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elbow this is the joint between links b and c and it has one degree of freedom actuated by a rc servo motor it can rotate to about 180° by design by link a the motion about the elbow is actuated by a set of gear trains

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web pick and place robot module block diagram 14 3 3 1 robotic arm design the robotic arm with gripper termination has five degrees of freedom with a rotating base that rests on the upper region of the vehicle as depicted in figure 6