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Modeling and Control of a Tracked Mobile Robot for Pipeline Inspection Michał Ciszewski, Mariusz Giergiel, Tomasz Buratowski, Piotr Małka, 2020-03-18 This book describes the design mathematical modeling control system development and experimental validation of a versatile mobile pipe inspection robot It also discusses a versatile robotic system for pipeline inspection together with an original adaptable tracked mobile robot featuring a patented motion unit Pipeline inspection is a common field of application for mobile robots because the monitoring of inaccessible long and narrow pipelines is a very difficult task for humans The main design objective is to minimize the number of robots needed to inspect different types of horizontal and vertical pipelines with both smooth and rough surfaces The book includes extensive information on the various design phases mathematical modeling simulations and control system development In closing the prototype construction process and testing procedures are presented and supplemented with laboratory and field experiments

Robotics, Vision and Control Peter Corke, 2023-05-09 This textbook provides a comprehensive but tutorial introduction to robotics computer vision and control It is written in a light but informative conversational style weaving text figures mathematics and lines of code into a narrative that covers robotics and computer vision separately and together as robotic vision Over 1600 code examples show how complex problems can be decomposed and solved using just a few simple lines of code This edition is based on Python and is accompanied by fully open source Python based Toolboxes for robotics and machine vision The new Toolboxes enable the reader to easily bring the algorithmic concepts into practice and work with real non trivial problems on a broad range of computing platforms For the beginning student the book makes the algorithms accessible the Toolbox code can be read to gain understanding and the examples illustrate how it can be used The code can also be the starting point for new work for practitioners students or researchers by writing programs based on Toolbox functions or modifying the Toolbox code itself

Robot Dynamics and Control Spong, 1989-05-24 **Robot Modeling and Kinematics** Rachid Manseur, 2007 Solutions manual to accompany simulation modeling and analysis Averill M. Law, W. David Kelton, 1981 **Solutions Manual, Fundamentals of Robot Mechanics** Gregory Long, 2015-08-01 A solutions manual for Fundamentals of Robot Mechanics by Gregory L Long **The Art of Modeling in Science and Engineering Solutions Manual** Diran Basmadjian, Steven Strauss, 2004-11-11 *Solutions Manual to Accompany Introduction to Robotics* John J. Craig, 1986

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