



Recipe Layered Taco Dip

Chao Zhang



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 elbow this is the joint between links b and c and it has one degree of freedom actuated by a rc servo motor it can rotate to
 about 1800 by design by link a the motion about the elbow is actuated by a set of gear brains

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 instructions to assemble the robot and connect the components we connected the servo motors ultrasonic sensor and quarky
 expansion board to the robot now you are ready to program your robot and explore its features

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web block diagram showing receiver of a pick n place robot the system consists of two motors for providing motion to the
 whole robot and two other motors to provide the arm motion the end effector or the gripper needs to be controlled to apply
 proper pressure on the object to handle it effectly to give it a soft grip

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web here programmable logic and controller is used for controlling and operating robotic arm all the various problems of this
 process have been analyzed properly and have been taken into consideration while programming and designing the pick and
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web based on the user commands the robot moves and pick and place the objects the robotic arm used here is similar to a human arm which is programmed to perform the pick and place functions the remainder of this paper is organized as follows the section 2 provides information about the existing works section 3 gives details of the proposed

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